# Facility location

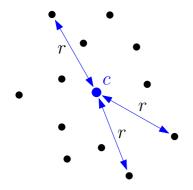
Given a set P of n sites in the plane,

find the point c that minimises the distance r to the furthest point(s) of P

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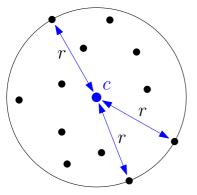
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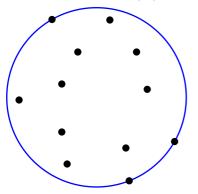
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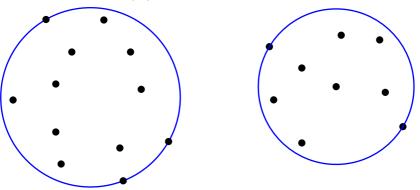
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Given a set P of n points in the plane, find the smallest circle  ${\cal C}(P)$  that contains all points of P

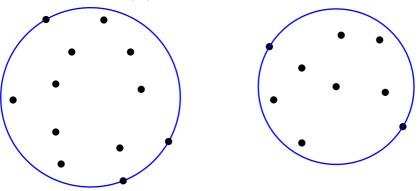


Given a set P of n points in the plane, find the smallest circle C(P) that contains all points of P



C(P) is either a circle defined by a set  $S\subseteq P$  of *three* points on the boundary, or a circle defined by a set  $S\subseteq P$  of *two* diametrically opposite points

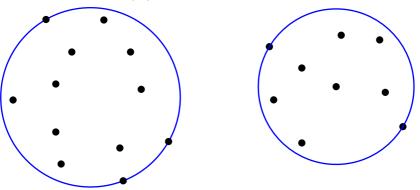
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Why not more than three points? Why not less than two points? Why not two points that are not diametrically opposite?

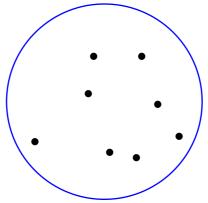
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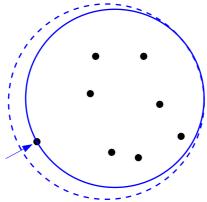
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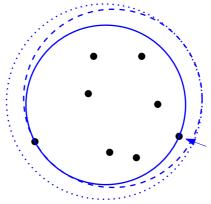
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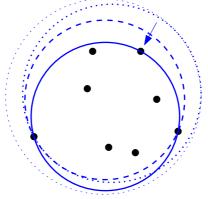
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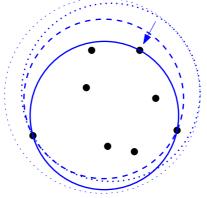
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Why not more than three points? Three points define a unique circle Why not less than two points? Could make circle smaller until there are two Why not two points that are not diametrically opposite? Smaller again

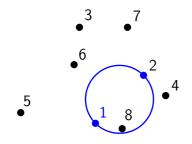
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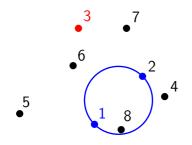
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Trivial algorithm: for all  $\Theta(n^3)$  pairs and triples of points that define a circle, test if all other  $\Theta(n)$  points lie inside; choose the smallest circle that passes the test  $\to \Theta(n^4)$  time

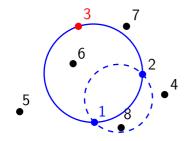
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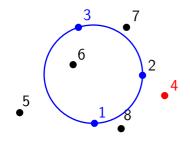
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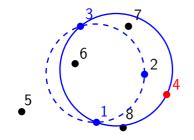
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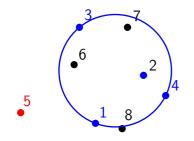
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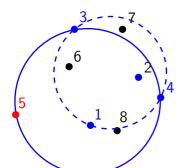
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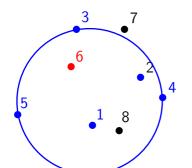
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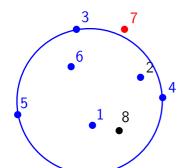
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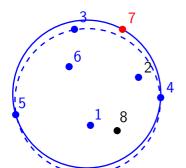
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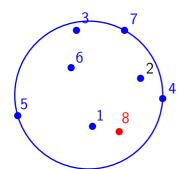
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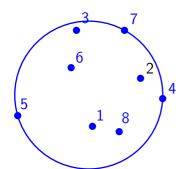
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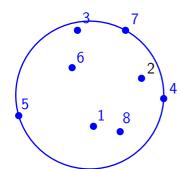
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Why does this work? (sketch)

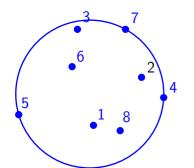
SEC(P, i) is defined by some set  $S \subseteq P[1..i]$ on the boundary of SEC(P, i);  $|S| \leq 3$ .

$$P[i] \notin S \to \operatorname{SEC}(P,i) = \operatorname{SEC}(P,i-1)$$

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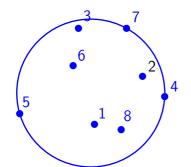
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$$\begin{split} P[i] \notin S &\to \operatorname{SEC}(P, i) = \operatorname{SEC}(P, i-1),\\ \text{so } \operatorname{SEC}(P, i) &\neq \operatorname{SEC}(P, i-1) \to P[i] \in S; \end{split}$$

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 $P[i] \notin S \to SEC(P, i) = SEC(P, i - 1),$ so  $SEC(P, i) \neq SEC(P, i - 1) \to P[i] \in S;$ in other words:  $P[i] \notin SEC(P, i - 1) \to P[i] \in S$ 

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### Algorithm SEC1(P, n, p)

Input: an array P with points in the plane; a number  $n \ge 1$ Output: smallest circle containing all points of P[1..n] with p on boundary

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\begin{array}{l} C \leftarrow \text{circle defined by } p \text{ and } P[1] \\ \text{for } i \leftarrow 2 \text{ to } n \\ \text{do if } P[i] \text{ does not lie in } C \\ \text{ then } C \leftarrow \text{s.e.c. of } P[1..i] \text{ with } P[i] \text{ and } p \text{ on boundary} \\ \text{return } C \end{array}
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Algorithm SEC(P, n) (smallest circle enclosing P[1..n])

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Algorithm SEC1(P, n, p) (small. circle encl. P[1..n] with p on boundary)  $C \leftarrow$  circle defined by p and P[1]for  $i \leftarrow 2$  to ndo if P[i] does not lie in C then  $C \leftarrow$  SEC2(P, i - 1, P[i], p)return C

Algorithm SEC2(P, n, p, q) (sm. circ. encl. P[1..n] with p, q on bound.)

 $C \leftarrow \text{circle defined by } p \text{ and } q$ for  $i \leftarrow 1$  to ndo if P[i] does not lie in C then  $C \leftarrow \text{circle defined by } p, q \text{ and } P[i]$ return C

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Algorithm SEC2(P, n, p, q)Worst-case running time: \Theta(n)C \leftarrow circle defined by p and qfor i \leftarrow 1 to ndo if P[i] does not lie in C then C \leftarrow circle defined by p, q and P[i]return C
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Worst case takes into account that line 3 of SEC may call SEC1 for every i, and line 3 of SEC1 may call SEC2 for every i. But this does not always happen, only if P[i] does not lie in C.

What about average expected running time?

Algorithm SEC(P, n)Worst-case running time: $C \leftarrow$  circle defined by P[1] and P[2] $\Theta(1) + \sum_{i=3}^{n} O(i^2) = O(n^3)$ for  $i \leftarrow 3$  to ndo if P[i] does not lie in C then  $C \leftarrow SEC1(P, i - 1, P[i])$ return C

Worst case takes into account that line 3 of SEC may call SEC1 for every i, and line 3 of SEC1 may call SEC2 for every i. But this does not always happen, only if P[i] does not lie in C.

What about *average expected* running time? IMPOSSIBLE TO SAY: maybe the data in our application has some structure that often brings out the worst-case behaviour (e.g. with points on a line from left to right: SEC calls SEC1 for every i)

Algorithm SEC(P, n) (smallest circle enclosing P[1..n])

randomly permute the points in P[1..n]  $C \leftarrow$  circle defined by P[1] and P[2]for  $i \leftarrow 3$  to ndo if P[i] does not lie in C then  $C \leftarrow \text{SEC1}(P, i - 1, P[i])$ return C

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randomly choose a permutation  $\pi$  of P[1..n] according to a uniform probability distribution on all n! permutations of P[1..n]; apply  $\pi$  to P[1..n]

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Algorithm SEC1(P, n, p) (small. circle encl. P[1..n] with p on boundary)

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**Algorithm** SEC2(P, n, p, q) (unchanged, still running in  $\Theta(n)$  time)

. . .

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Only happens if P[i] is one of the one or two points in P[1..i] that, together with p, define SEC1(P, i, p). What is the probability q that this happens?

Algorithm SEC(P, n) (smallest circle enclosing P[1..n])

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