

# Faces of a Convex Polytope (Chapter 5.3)

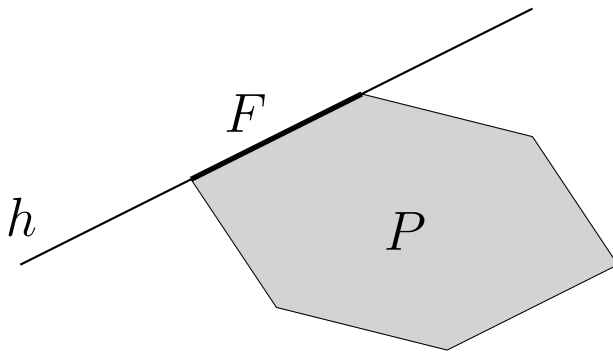
Faces of the 3-dimensional cube

- 8 “corners” called vertices
- 12 edges
- 6 “squares” called facets

## Definition (Face)

A face of a convex polytope  $P$  is defined as

- either  $P$  itself, or
- a subset of  $P$  of the form  $P \cap h$ , where  $h$  is a hyperplane such that  $P$  is fully contained in one of the closed half-spaces determined by  $h$



Each face of a convex polytope  $P$  is a convex polytope

- $P$  is the intersection of finitely many half-spaces, and  $h$  is the intersection of two half-spaces.
- So the face is an  $H$ -polyhedron, and it is bounded

A face of dimension  $j$  is called  $j$ -face. If  $P$  is a polytope of dimension  $d$ , then its faces have dimensions  $-1, 0, 1, \dots, d$ , where  $-1$  is the dimension of the empty set.

## Names of faces

- 0-faces are called *vertices*
- 1-faces are called *edges*
- $(d - 1)$ -faces are called *facets*
- $(d - 2)$ -faces are called *ridges*

The 3-dimensional cube has 28 faces in total: the empty face, 8 vertices, 12 edges (ridges), 6 facets, and the whole cube.

Definition of an *extremal point* of a set

For a set  $X \subseteq \mathbb{R}^d$ , a point  $x \in X$  is *extremal* if  $x \notin \text{conv}(X \setminus \{x\})$

**Main Proposition.** Let  $P \subset \mathbb{R}^d$  be a (bounded) convex polytope

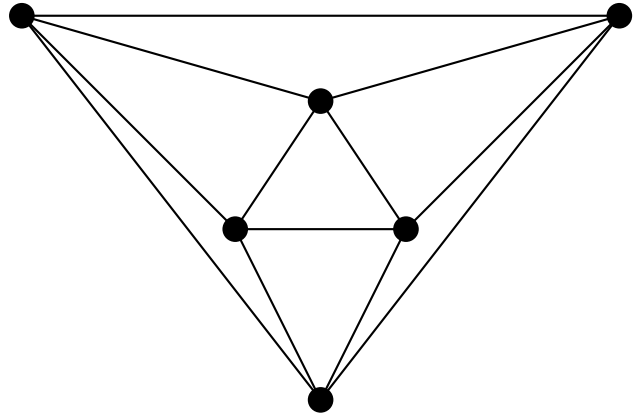
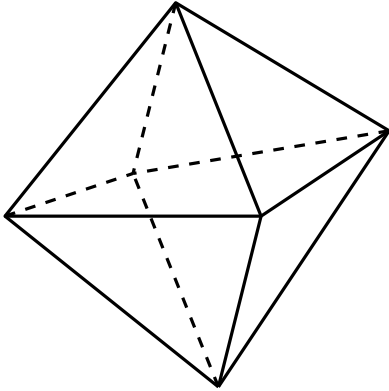
- (i) (“Vertices are extremal”) The extremal points of  $P$  are exactly its vertices, and  $P$  is the convex hull of its vertices
- (ii) (“Face of a face is a face”) Let  $F$  be a face of  $P$ . The vertices of  $F$  are exactly those vertices of  $P$  that lie in  $F$ . More generally, the faces of  $F$  are exactly those faces of  $P$  that are contained in  $F$

The above proposition has two implications.

- Each  $V$ -polytope is the convex hull of its vertices
- The faces can be described combinatorially: they are convex hulls of certain subsets of vertices.

## Graph of polytopes

- The vertices of the polytope are vertices of the graph
- Two vertices are connected by an edge in the graph if they are vertices of the same edge of  $P$



For any convex polytope in  $\mathbb{R}^3$ , the graph is always planar

- Project the polytope from its interior point onto a circumscribed sphere
- make a “cartographic map” of this sphere, say stereographic projection

This graph is vertex 3-connected. (A graph  $G$  is called vertex  $k$ -connected if  $|V(G)| \geq k + 1$  and deleting any at most  $k - 1$  vertices leaves  $G$  connected.)

### Steinitz Theorem

A finite graph is isomorphic to the graph of a 3-dimensional convex polytope if and only if it is planar and vertex 3-connected.

Graphs of higher-dimensional polytopes probably have no nice description comparable to the 3-dimensional case.

- It is likely that the problem of deciding whether a given graph is isomorphic to a graph of a 4-dimensional convex polytope is NP-hard
- The graph of every  $d$ -dimensional polytope is vertex  $d$  connected (Balinski’s theorem), but this is only a necessary condition

# Examples

## Simplex

A  $d$ -dimensional simplex has been defined as the convex hull of a  $(d+1)$ -point affinely independent set  $V$ .

- It is easy to see that each subset of  $V$  determines a face of the simplex
- There are  $\binom{d+1}{k+1}$  faces of dimension  $k$ ,  $k = -1, 0, \dots, d$ , and  $2^{d+1}$  faces in total

## Crosspolytope

The  $d$ -dimensional crosspolytope has  $V = \{e_1, -e_1, \dots, e_d, -e_d\}$  as the vertex set.

- A proper subset  $F \subset V$  determines a face if and only if there is no  $i$  such that both  $e_i \in F$  and  $-e_i \in F$
- There are  $3^d + 1$  faces, including the empty one and the whole crosspolytope

## Cube

The nonempty faces of the  $d$ -dimensional cube correspond to vectors  $v \in \{-1, 1, 0\}^d$ .

- The face corresponding to such  $v$  has the vertex set  $\{u \in \{-1, 1\}^d \mid u_i = v_i \text{ for all } i \text{ with } v_i \neq 0\}$ .

## Face Lattice

Let  $\mathcal{F}(P)$  be the set of all faces of a (bounded) convex polytope  $P$  (including the empty face  $\emptyset$  of dimension  $-1$ ).

- We consider the partial ordering of  $\mathcal{F}(P)$  by inclusion

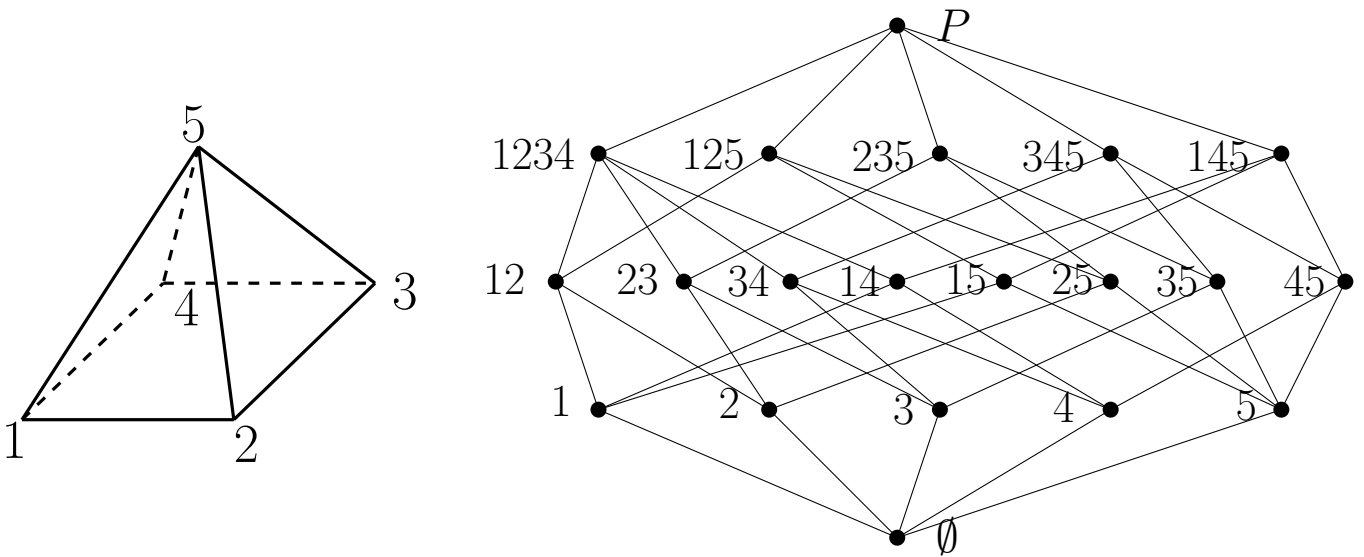
## Definition of Combinatorial Equivalence

Two convex polytopes  $P$  and  $Q$  are called combinatorially equivalent if  $\mathcal{F}(P)$  and  $\mathcal{F}(Q)$  are isomorphic as partially ordered sets.

$\mathcal{F}(P)$  is a lattice (due to the partially ordered set). Recall the following two conditions:

- *Meet condition:* For any two faces  $F, G \in \mathcal{F}(P)$ , there exists a face  $M \in \mathcal{F}(P)$ , called the *meet* of  $F$  and  $G$ , that is contained in both  $F$  and  $G$  and contains all other faces contained in both  $F$  and  $G$
- *Join condition:* For any two faces  $F, G \in \mathcal{F}(P)$ , there exists a face  $J \in \mathcal{F}(P)$ , called *join* of  $F$  and  $G$ , that contains both  $F$  and  $G$  and is contained in all other faces containing both  $F$  and  $G$

The meet of two faces is their geometric intersection  $F \cap G$ .



The face lattice can be a suitable representation of a convex polytope in a computer

- Each  $j$ -face is connected by pointers to its  $(j-1)$ -faces and to the  $(j+1)$ -faces containing it
- It is a somewhat redundant representation
  - The vertex-facet incidences already contain the full information
  - For some applications, even less data may be sufficient, say the graph of the polytope

**The dual polytope.** Let  $P$  be a convex polytope containing the origin in its interior. Then the dual set  $P^*$  is also a polytope.

## Propoistion

For each  $j = -1, 0, \dots, d$ , the  $j$ -faces of  $P$  are in a bijective correspondence with the  $(d - j - 1)$ -faces of  $P^*$ . This correspondence also reverses inclusion. The face lattices of  $P^*$  arises by turing the face of  $P$  upside down.

## Example

- The cube and the octahedron are dual to each other
- the dodecahedron and the icosahedron are also dual to each other
- the tetrahedron is dual to itself.

If we have a 3-dimensional convex polytope and  $G$  is its graph, then the graph of the dual polytope is the dual graph to  $G$ .

More generall, we have

- The dual of a  $d$ -simplex is a  $d$ -simplex
- The  $d$ -dimensional cube and the  $d$ -dimensional crosspolytope are dual to each other.

## Definition of Simple and Simplicial polytopes

- A polytope  $P$  is called *simplicial* if each of its facets is a simplex
  - This happens if the vertices of  $P$  are in general position, but general position is not necessary.
- A  $d$ -dimensional polytope  $P$  is called *simple* if each of its vertices are contained in exactly  $d$  facets.

## Illustrations

- Since the faces of a simplex are again simplices, each proper face of a simplicial polytope is a simplex
- Simplicial polytopes: tetrahedron, octahedron, and icosahedron
- Simple polytopes: tetrahedron, cube, and dodecahedron
- 4-sided pyramid is neighbor simplicial nor simple

## Duality

The dual of a simple polytope is simplicial, and vice versa

- For a simple  $d$ -dimensional polytope, a small neighborhood of a vertex of the  $d$ -dimensional cube
- For each vertex  $v$  of a  $d$ -dimensional simple polytope, there are  $d$  edges emanating from  $v$ , and each  $k$ -tuple of these edges uniquely determines one  $k$ -face incident to  $v$ .
- $v$  belongs to  $\binom{d}{k}$   $k$ -faces,  $k = 0, 1, \dots, d$ .